

# VueOne

LiDAR Based ADAS by Vueron



Make your customer safer with Vueron

## Proven LiDAR system with LiDAR-only AV fleet

Vueron has developed a LiDAR-only autonomous driving solution, which uses only LiDAR sensor(s) and no cameras, radars, GPS, or HD maps. Vueron's AV development fleet has been tested on real roads worldwide



Korea AV #1



Korea AV #2



California AV #3



Nevada AV #4

## Cost effective automotive processor

The VueOne system works in real time and is deployed on automotive qualified processors, which are already in serial production by global automotive OEMs for camera-based ADAS systems. Proven, cost effective processors can be used for serial productions



Renesas R-Car H3



TI TDA4VM



Renesas R-Car V3H

### Processor Minimum requirements

CPU : Arm Cortex-A57  
 Frequency : Over 1.8GHz  
 Memory : Over 4MB

## Working with automakers

Intensive experience with global automakers and suppliers in LiDAR solutions ranging from LiDAR modules, truck platooning, autonomous shuttles, autonomous trucks, and more



Autonomous shuttle



Multi LiDAR solution



Truck platooning



Autonomous vehicle

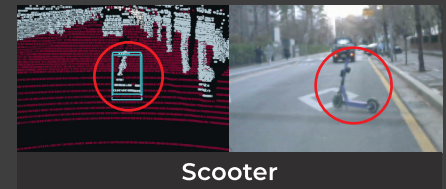
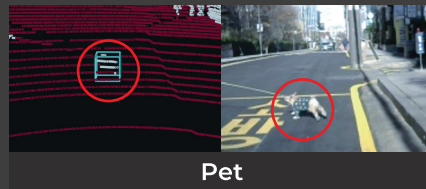
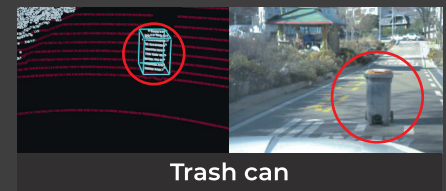
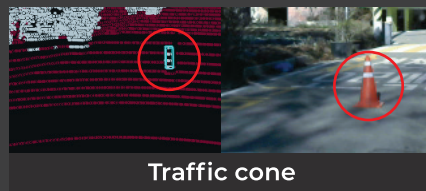
## Key Specifications

Basic Output Information		Description
Object Info.	ID	object ID
	Age	object age
	Bounding Box	8 points for 3D box
	Contour	contour points
	Type	passenger vehicle, commercial vehicle, pedestrian, cyclist, unknown
	Velocity	value and direction
Lane Info.	Left Lane Valid	valid flag for lane
	Right Lane Valid	valid flag for lane
	Left Lane Function	parameters for 3rd equation
	Right Lane Function	parameters for 3rd equation
Ground Info.	Freespace	occupied grid map



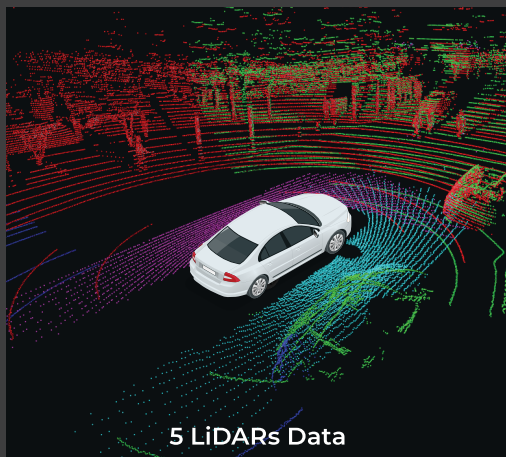
# Additional Features 01

## Road obstacle detection



# Additional Features 02

## Multi-LiDAR sensors calibration



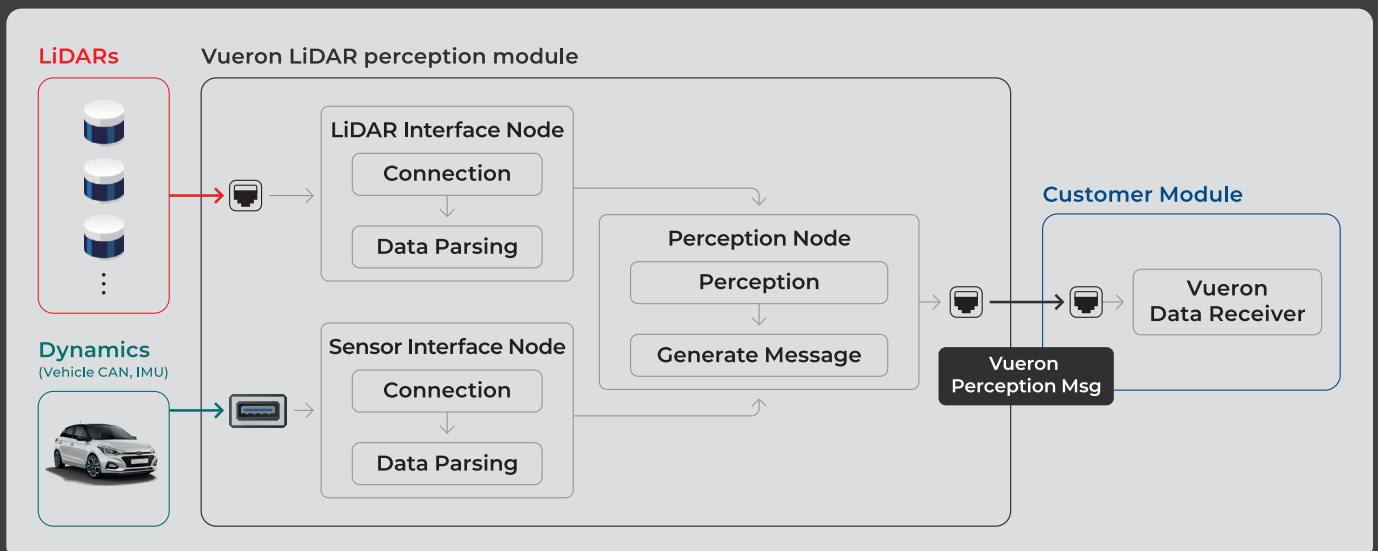
## Sensor mounting position



## Vehicle type



# System Configurations





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